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X8718-097-50

86.00/3.390

96.00/3.780

1274.51/9

1480/8.09

Bipolar 5.95/2.70

1.8°

5.0

0.61

4

MOTOR SPECIFICATIONS

Part Number

Step Angle

Frame Size (mm/in)

"A" Body Length (mm/in)

Holding Torque (oz-in/Nm) Resistance (Ohms/Phase)

Rotor Inertia (g-cm²/ oz-in²)

Current (Amps/Phase)

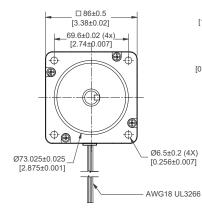
Number of Leads

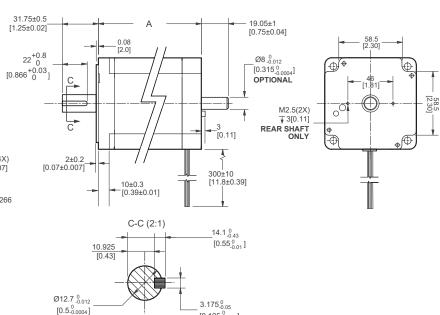
Weight (lbs/kg)

Connection



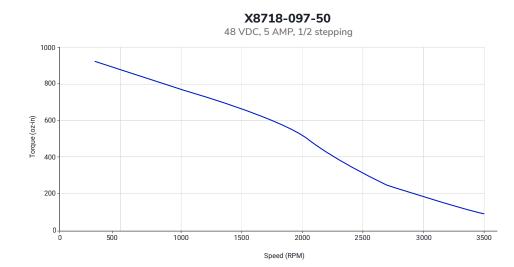
DIMENSIONS





[0.125_0_02]

PERFORMANCE CURVE



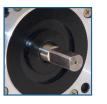
OPERATING SPECIFICATIONS

Radial Play	0.03 mm @ 0.45 kg (0.001 in @ 1.00 lbs)
End Play	0.08 mm @ 1.36 kg (0.003 in @ 3.00 lbs)
Shaft Run Out	0.05 TIR (0.002 TIR)
Concentricity of Mounting Pilot to Shaft	0.08 TIR (0.003 TIR)
Perpendicularity of Mounting Pilot to Face	0.08 TIR (0.003 TIR)
Max Radial Load at Dimension "K" from mount- ing face	17.69 kg (39.00 lbs)
Dimension"K"	15.74 mm (0.62 in)
Max Axial Load	6.80 kg (15.00 lbs)
Maximum Case Temperature	80°C (176°F) Maximum
Ambient Temperature	-20°C to 50°C (-4 to 122°F)
Storage Temperature	-20°C to 100°C (-4 to 212°F)
Humidity Range (%)	85% or less, non-condensing
Magnet Wire Insulation	Class B 130 ° C
Insulation Resistance	100M Ohm at 500 VCD
Dielectric Strength	500 VCD for 1 min.

OPERATION & USAGE TIPS



Do not disassemble motors; a significant reduction in motor performance will occur.



Do not machine shafts; this will have a negative effect on shaft run out and perpendicularity.



Do not disconnect motor from drive while in operation.



Do not use holding torque/detent torque of motor as a fail safe brake.



Do not hold motor by lead wires.



Do not exceed the rated current; this wil burn the motor.

FAILURE TO COMPLY WITH THESE RECOMMENDATIONS WILL VOID ALL WARRANTY TERMS





Power Supply **PW-150-24**



Stepper Driver+Controller **R356**



Stepper Driver **R710**

Motion Control, Solved. MOTOR ENGINEERING & MANUFACTURING









Small Batch to OEM Volume Production



US Based Support & Manufacturing